

Electrical and Mechanical Characteristics

1. The electrical and mechanical characteristics of inner shaft refer to VID29 spec.

2. The following list is only for out shaft

$T_{amb}=25^{\circ}\text{C}$, In micro step mode @ Max. voltage 4.2V, unless other specified.

Parameter	Symbol	Test Conditions	Min.	Typ.	Max	Units
Electrical Characteristics						
Operating Temperature	T_a		-40		105	$^{\circ}\text{C}$
Coil Resistance	R_b			280		Ω
Operating Current	I_m	$f_a=200\text{Hz}$			20	mA
Start-Stop Frequency	f_{ss}	$J_L=0.2 \times 10^{-6} \text{kgm}^2$	125			Hz
Maximum Driving Frequency	f_{mm}	$J_L=0.2 \times 10^{-6} \text{kgm}^2$	400			Hz
Mechanical Characteristics						
Dynamic Torque	M200	$f_a=200\text{Hz}$		1.1		mNm
	M400	$f_a=400\text{Hz}$		0.7		mNm
Static Torque	M_s	$U_b=5\text{V}$	3.5	4.0		mNm
Equivalent Motor Inertia @ Output	J_m			5.064 E-7		Kgm^2
Gear ratio				180:1		
Step size in full step mode				1		Degree
Step size in partial step mode				1/3		Degree
Step size in micro step mode				1/12		Degree
Backlash				0.7		Degree
Noise						
Noise Level	SPL	@200°/sec		46		dBA
Others						
Angle of Rotation	f_i	Motors with internal Stop			280	Degree
Force allowed on the pointer shaft:						
Axial force (push)	F_a				60	N
Axial force (pull)	F_a				60	N
Perpendicular force	F_q				6	N
Imposed acceleration	α_p				1000	rad/s^2
Number of allowed pointer insertion					1	Time

Note: f_a – full-step frequency J_L – Load inertia