

ELECTRICAL AND MECHANICAL CHARACTERISTICS

T_{amb}=25°C, in partial step mode @ Max. voltage 5V, unless other specified.

| Parameter | Symbol | Test Conditions | Min. | Typ. | Max. | Units |
|-------------------------------------|----------------|---|------|------|------|--------------------|
| Operating Temperature | T _a | | -40 | | 105 | °C |
| Coil Resistance | R _b | | 235 | 260 | 285 | Ω |
| Operating Peak Current | I _m | f _a =16Hz(50°/s) | | 19.3 | 21.3 | mA |
| Dynamic Torque | M50 | f _a =16Hz(50°/s) | 0.4 | 0.5 | | mNm |
| | M200 | f _a =66Hz(200°/s) | | 0.4 | | |
| Static Torque | M _s | U _b =5V | 1 | 1.2 | | mNm |
| | M ₀ | U _b =0V | 0.16 | 0.25 | | |
| Gear Play | | | | ±0.5 | ±1 | Degree |
| Force allowed on the pointer shaft: | | | | | | |
| Axial force (push) | F _a | | | | 100 | N |
| Axial force (pull) | F _a | | | | 70 | N |
| Perpendicular force | F _q | | | | 7 | N |
| Imposed acceleration | α _p | | | | 1000 | Rad/s ² |
| Noise Level | SPL | Back ground:35dBA F _a =16Hz | | 40 | 50 | dBA |

Note: f_a – full-step frequency